



CERTIFICATE FOR  
**Highly Cited Research**

in Information Fusion

Awarded **December, 2016** to

**Z. Wang**

in recognition of the contribution to the quality of the journal made by:

**Distributed weighted robust Kalman filter fusion for uncertain systems with autocorrelated and cross-correlated noises\***

*\*paper published in 2013 and cited in 2014/2015 up until June 2016 according to data from Scopus*

The Editors of  
Information Fusion

